



UNIVERSITY OF
EASTERN FINLAND

Modeling uncertainties of aerosol properties and processes

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Väinö Hämmäläinen, Teemu Salminen



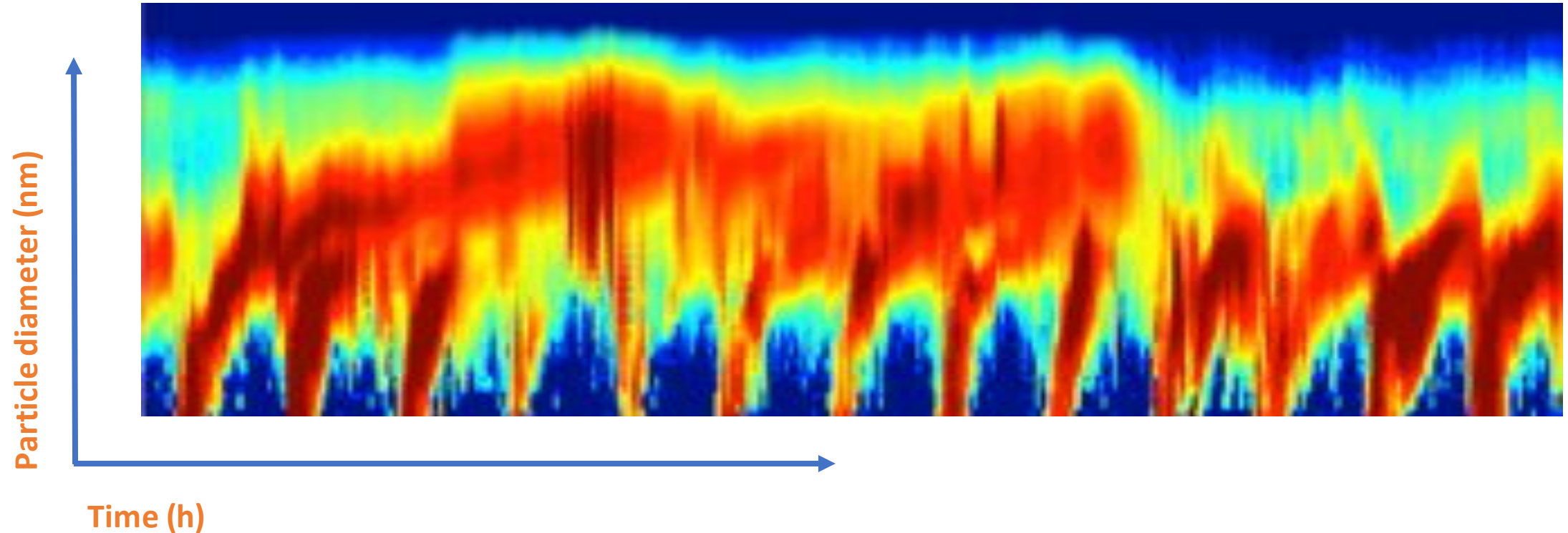
VILMA
CoE

Virtual laboratory for molecular level
atmospheric transformations



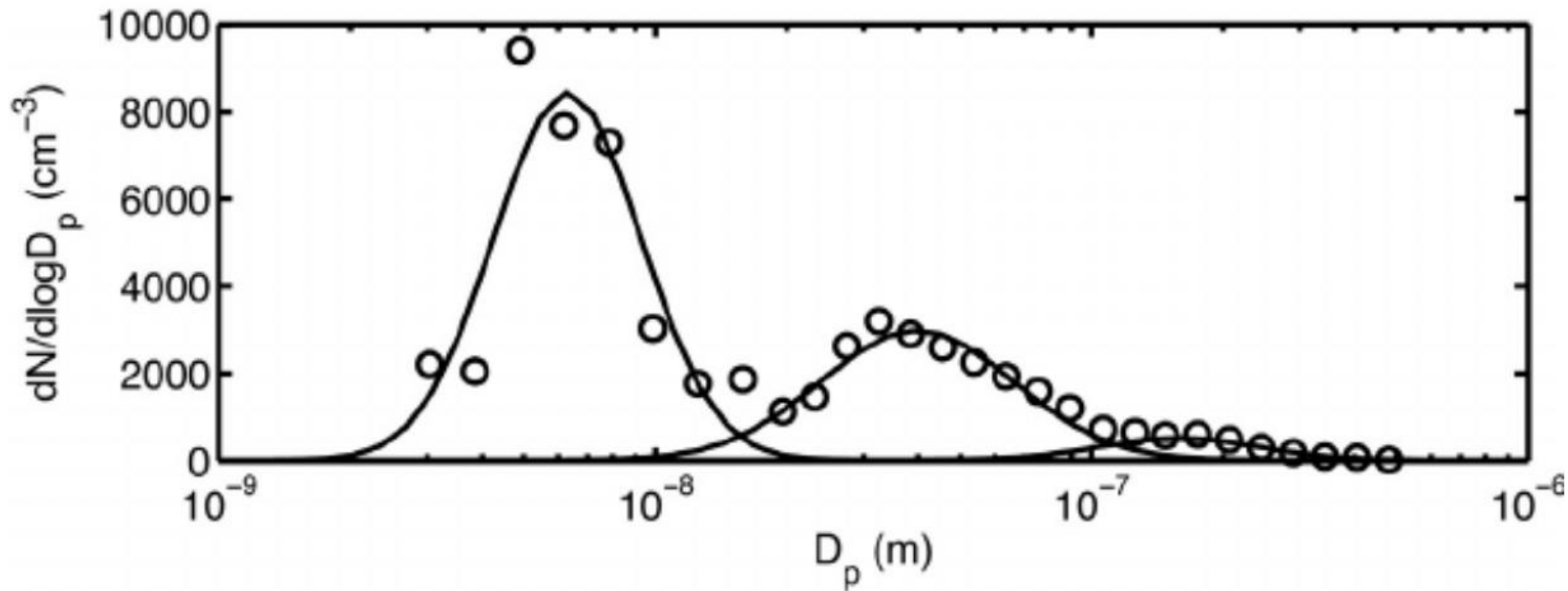
Finnish Centre of Excellence
in Inverse Modelling and Imaging

Sequential particle counter measurements



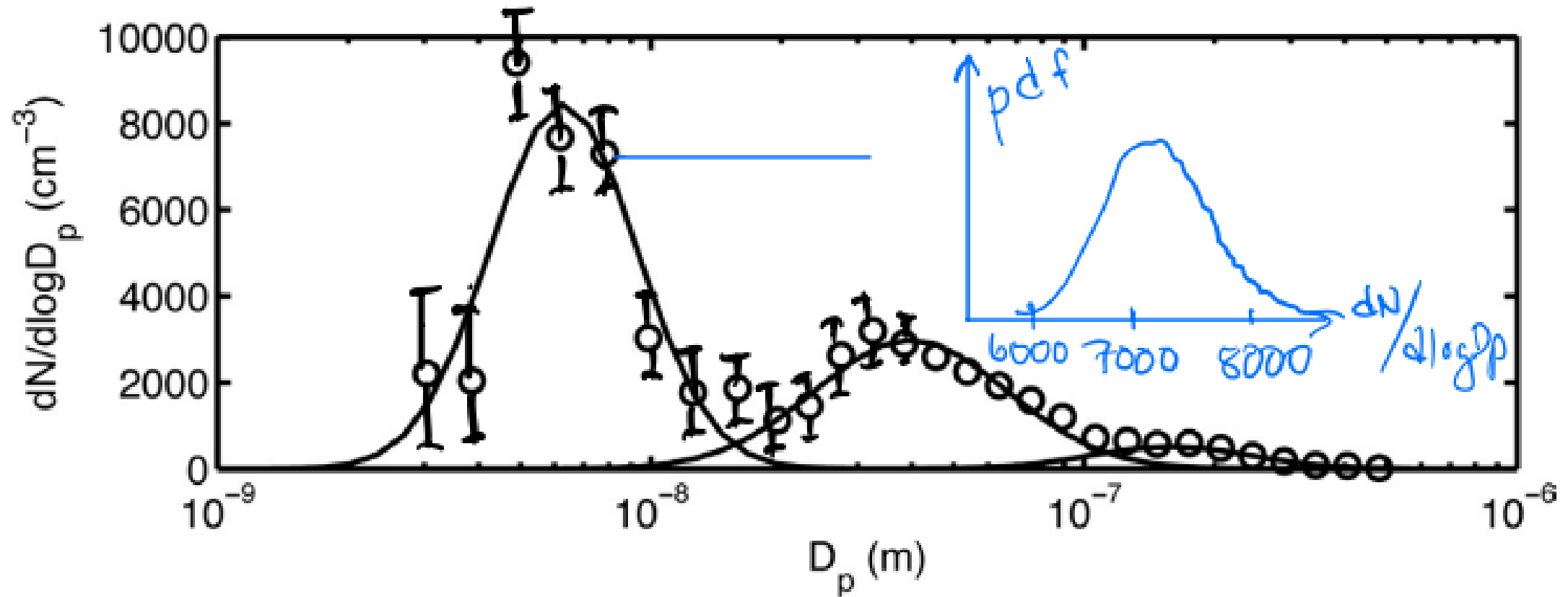
- Aims:**
- Reconstruct the particle size distribution, with uncertainties
 - Estimate the process rates (nucleation, condensational growth, deposition), with uncertainties

A typical number concentration distribution



Dal Maso et al. (2005)

Number concentration distribution as pdf:s



MEASUREMENT UNCERTAINTIES

Many aerosol measurement devices are based on classification by electrical mobility

Challenge:

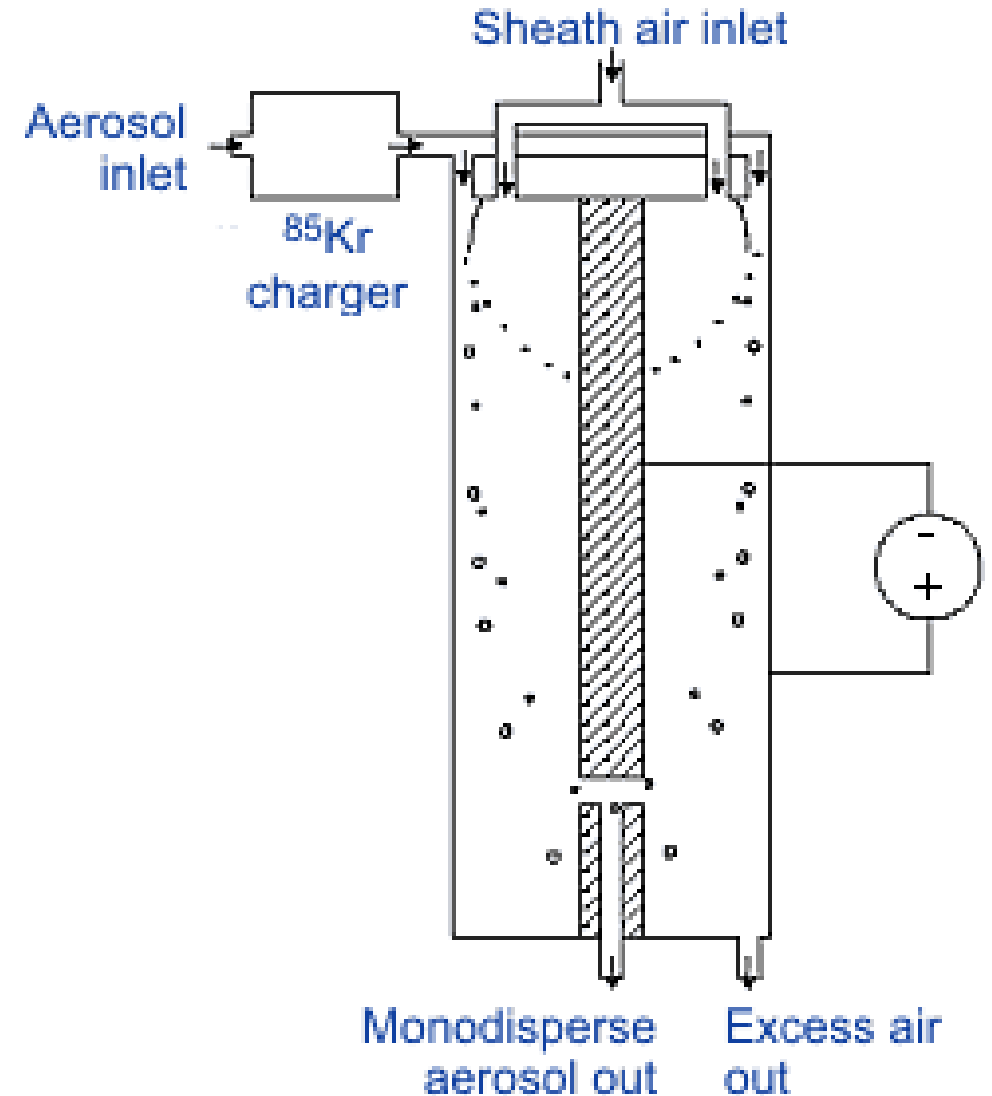
Charge as a function of particle size needs to be known

Our aim is to find out:

How uncertain are the charging probabilities?

Other sources of uncertainty:

Diffusion losses, low counting statistics



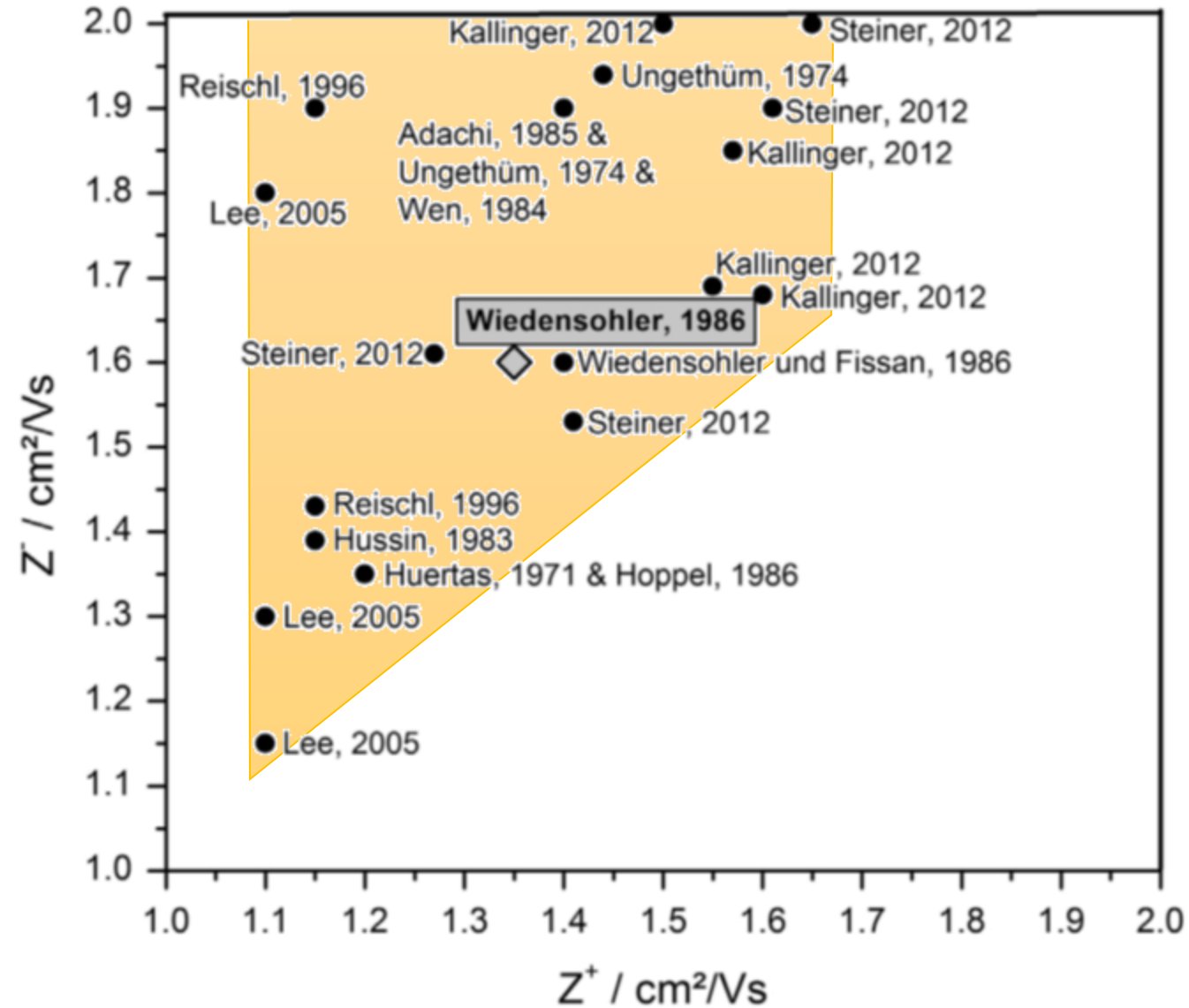
MODEL SETUP: (following Lopez-Yglesias&Flagan, 2013)

- Specify ion properties
- Boltzmann statistics for the steady state ion distributions
- Calculation of flux coefficients
- Solution of population balances



Charging probabilities for different charging states as a function of particle size
(Hoppel&Frick, 1986 -> Wiedensohler, 1988)

Variability in charger ion properties



CHARGING PROBABILITY UNCERTAINTY

Wiedensohler (xxxx) curve fits
as pale dotted lines.

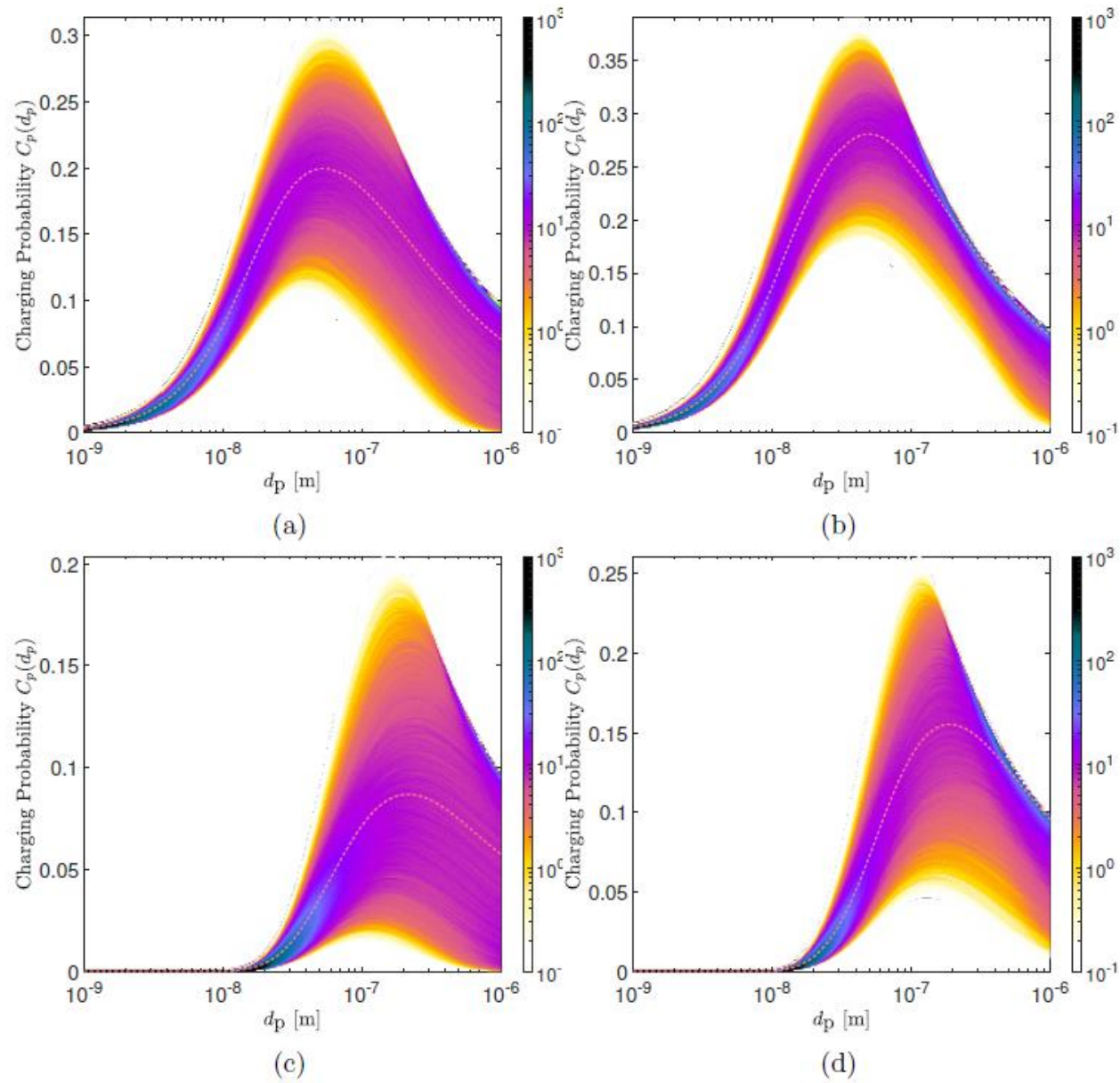
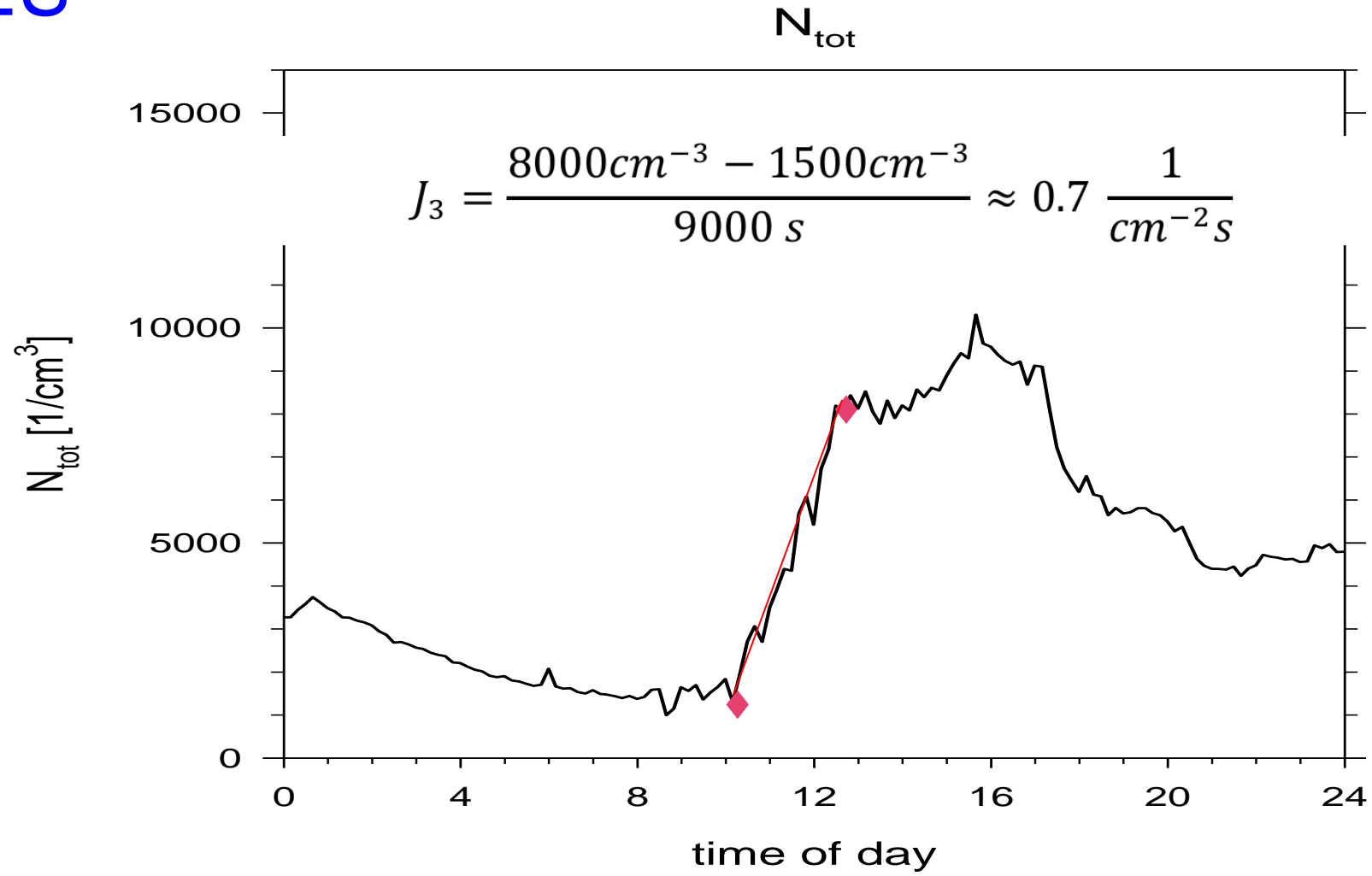


Figure 3: The curve densities corresponding to charge states: a) $p = 1$, b) $p = -1$, c) $p = 2$, d) $p = -2$, e) $p = 3$, and f) $p = -3$. The dashed orange lines show the respective charging probabilities evaluated at the expected values of the parameters.

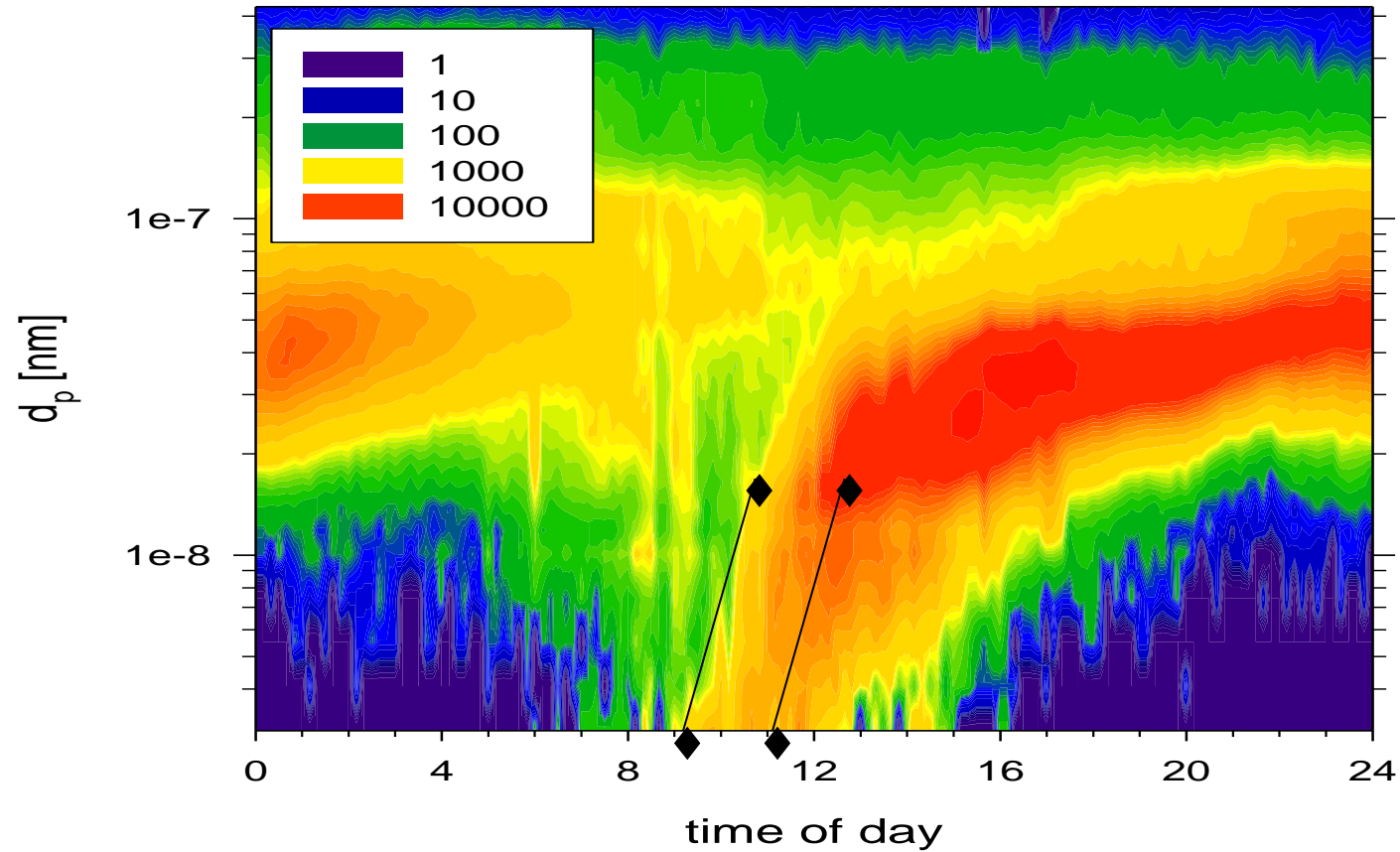
FORMATION RATES

May 19th, 1999



GROWTH RATES

$dN/d(\log d_p)$ - contours



$$GR \gg \frac{20nm - 3nm}{2h}$$
$$= 8.5 \frac{nm}{h}$$

ESTIMATION OF RATES: KALMAN FILTER

- An algorithm that is used to estimate system parameters, including those that cannot be measured directly
- Input: noisy and/or inaccurate and/or missing measurements
- Output: less noisy, more complete and more accurate estimates, with uncertainty estimations
- System parameters are modeled as probability density distributions
- Integrates physical knowledge and intuition into Bayesian inference
- Used widely e.g. in process control and tracking systems

BAYESIAN STATE ESTIMATION

- Sequence of measurements: y^1, \dots, y^T
- State variable (model unknowns) $X^k = [N_i^k \quad g_i^k \quad \lambda_i^k \quad J^k]$
- State-space model

$$X^{k+1} = F(X^k) + w^k \quad \longleftarrow \quad \text{Evolution model (GDE)}$$

$$y^k = HX^k + v^k \quad \longleftarrow \quad \text{Observation model (DMPS)}$$

- State estimation: Given y^1, \dots, y^t estimate X^k

$k > t$: Prediction
 $k = t$: Filtering
 $k < t$: smoothing

PHYSICAL KNOWLEDGE AND INTUITION

- Time evolution of the size distribution is described by the aerosol GDE

$$\begin{aligned}
 \frac{\partial n}{\partial t}(d_p, t) = & \underbrace{-\frac{\partial g(d_p, t)n(d_p, t)}{\partial d_p}}_{\text{growth by condensation}} - \underbrace{n(d_p, t) \int_{d_0}^{\infty} \beta(d_p, s)n(s, t)ds}_{\text{coagulation sink}} \\
 & + \underbrace{\frac{1}{2} \int_0^{d_p} \beta\left(\sqrt[3]{d_p^3 - q^3}, q\right)n\left(\sqrt[3]{d_p^3 - q^3}, t\right)n(q, t)dq}_{\text{coagulation source}} - \underbrace{\lambda(d_p, t)n(d_p, t)}_{\text{loss by deposition}}
 \end{aligned}$$

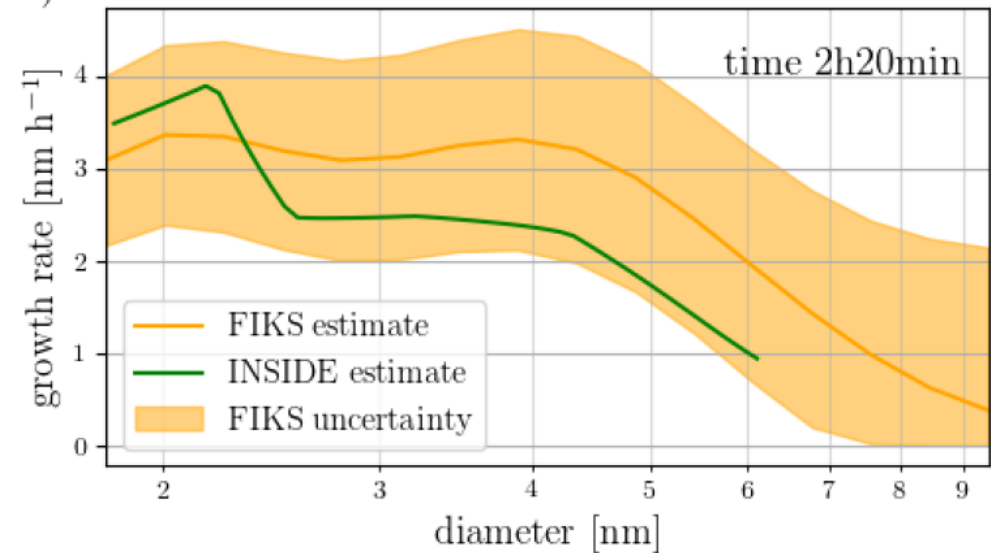
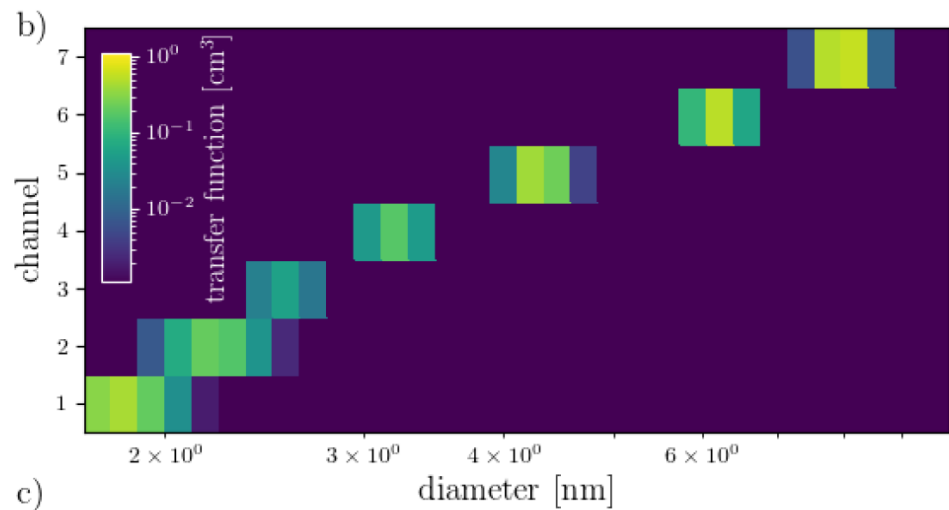
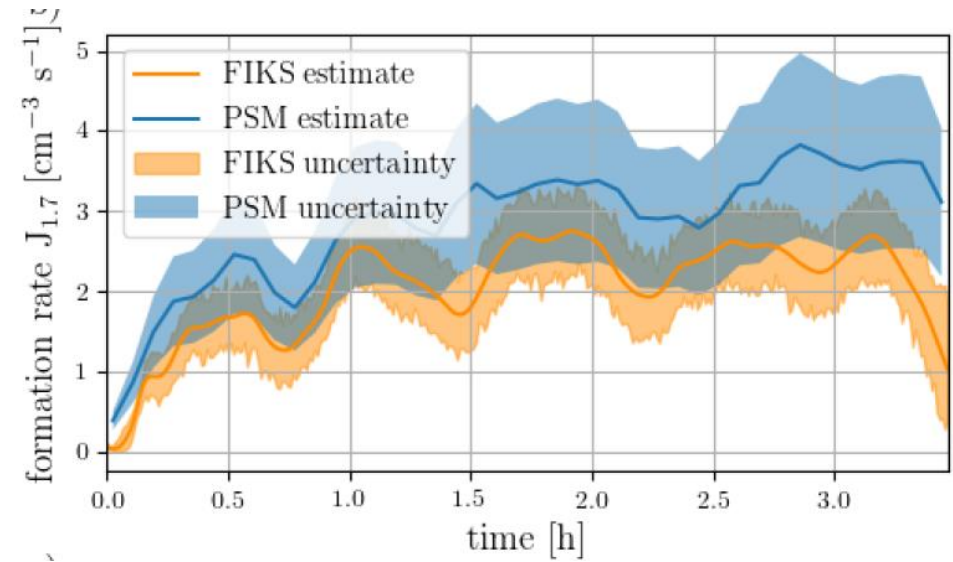
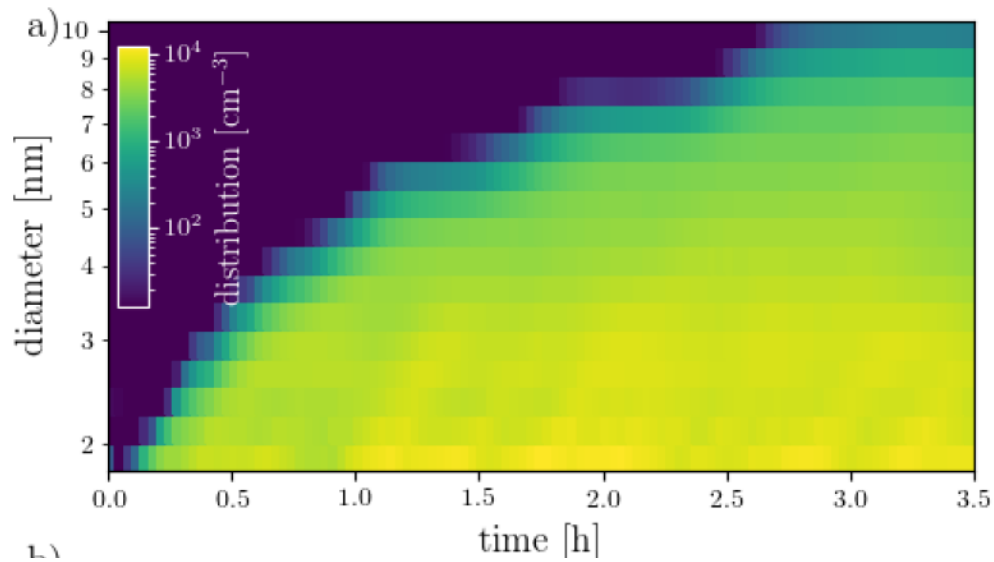
- Prior 'guesses' for the variables can be taken to make sense, and can include correlations both in time and size

General dynamic equation (GDE) of aerosols

Unknowns in the model
 $n(d_p, t)$, $g(d_p, t)$ and $\lambda(d_p, t)$
 and $J(t)$

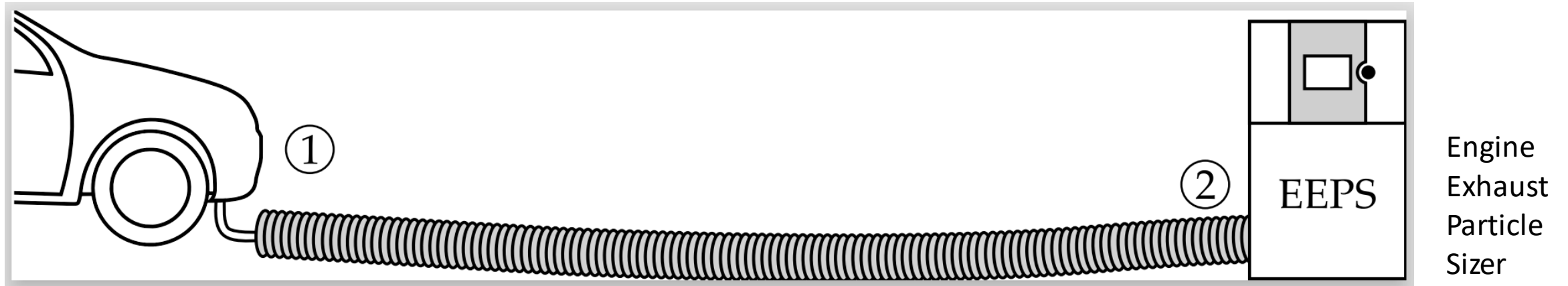
$$\begin{aligned}
 \frac{\partial n}{\partial t}(d_p, t) = & \underbrace{-\frac{\partial g(d_p, t) n(d_p, t)}{\partial d_p}}_{\text{growth by condensation}} - \underbrace{n(d_p, t) \int_{d_0}^{\infty} \beta(d_p, s) n(s, t) ds}_{\text{coagulation sink}} \\
 & + \underbrace{\frac{1}{2} \int_0^{d_p} \beta(\sqrt[3]{d_p^3 - q^3}, q) n(\sqrt[3]{d_p^3 - q^3}, t) n(q, t) dq}_{\text{coagulation source}} - \underbrace{\lambda(d_p, t) n(d_p, t)}_{\text{loss by deposition}}
 \end{aligned}$$

DMA-train measurements of sulphuric acid-ammonia nucleation and growth in CLOUD



Thanks to Lubna Dada and Dominik Stolzenburg who made the comparisons to CLOUD data possible

Example: Inverse modeling of coagulation and deposition with aerosol GDE & MCMC



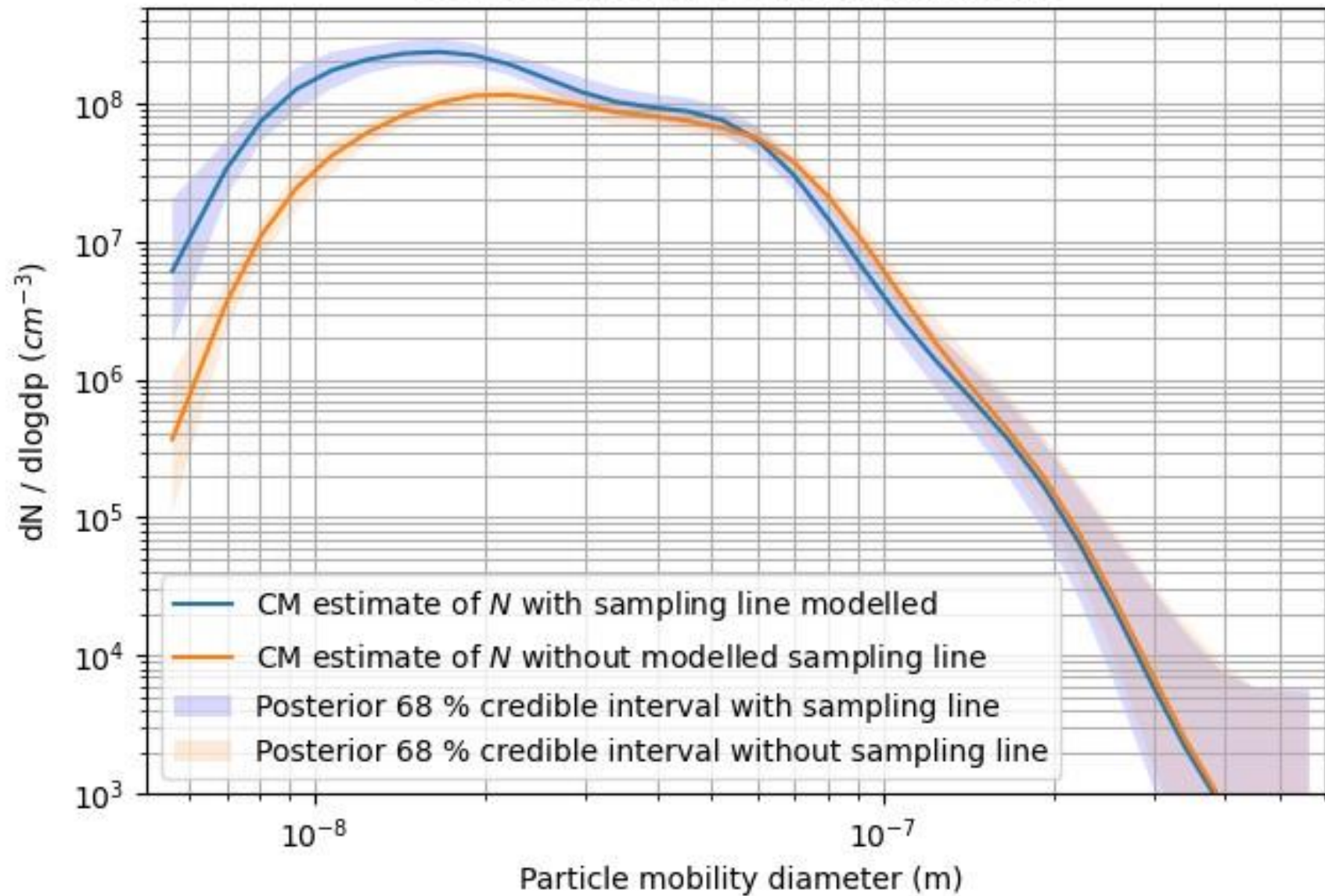
Variables with uncertainty:

Fractal shape parameters (fractal dimension, primary particle size)

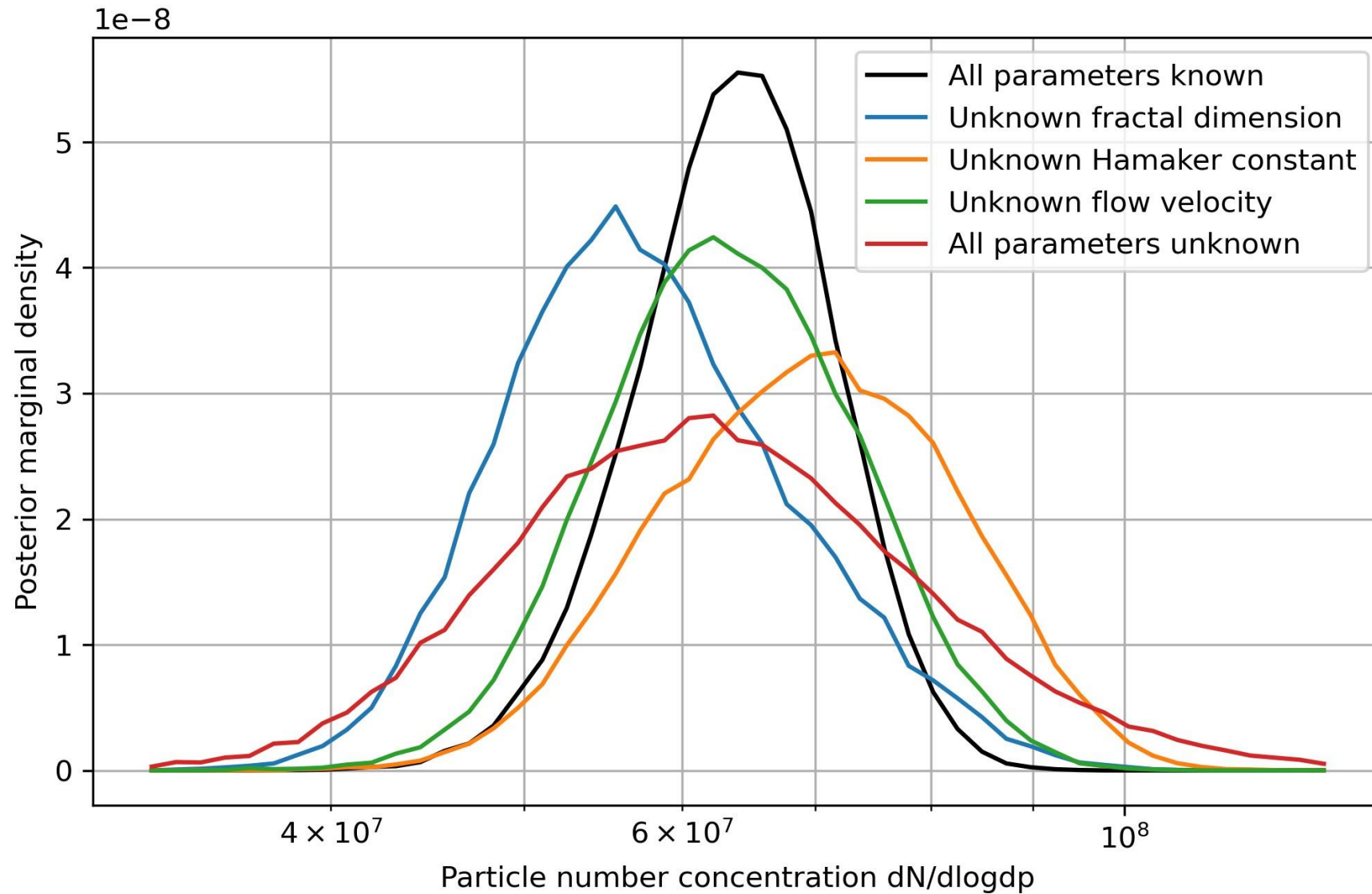
Van Der Waals force (Hamaker constant)

Flow velocity

Estimated particle size distributions



Marginal posterior densities computed using models with different unknowns





Retrieval of process rate parameters in the general dynamic equation for aerosols using Bayesian state estimation: BAYROSOL1.0

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Thank you!

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Aerosol formation and growth rates from chamber experiments using Kalman smoothing

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Uncertainty Analysis of the Aerosol Charge Distribution in a Bipolar Environment

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